
Interactive Graphics Using Parametric Equations (Day 2)

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Computer Science

Bezier Curves

Google “bezier curves”

- <http://www.doc.ic.ac.uk/~dfg/AndysSplineTutorial/Beziers.html/>

Interactive Graphics Curves

Uses:

- Design of Fonts and other printer symbols
- Consumer goods: shapes of cell phones, cars, etc.

Bezier Curves

Curve is specified by 2 equations:

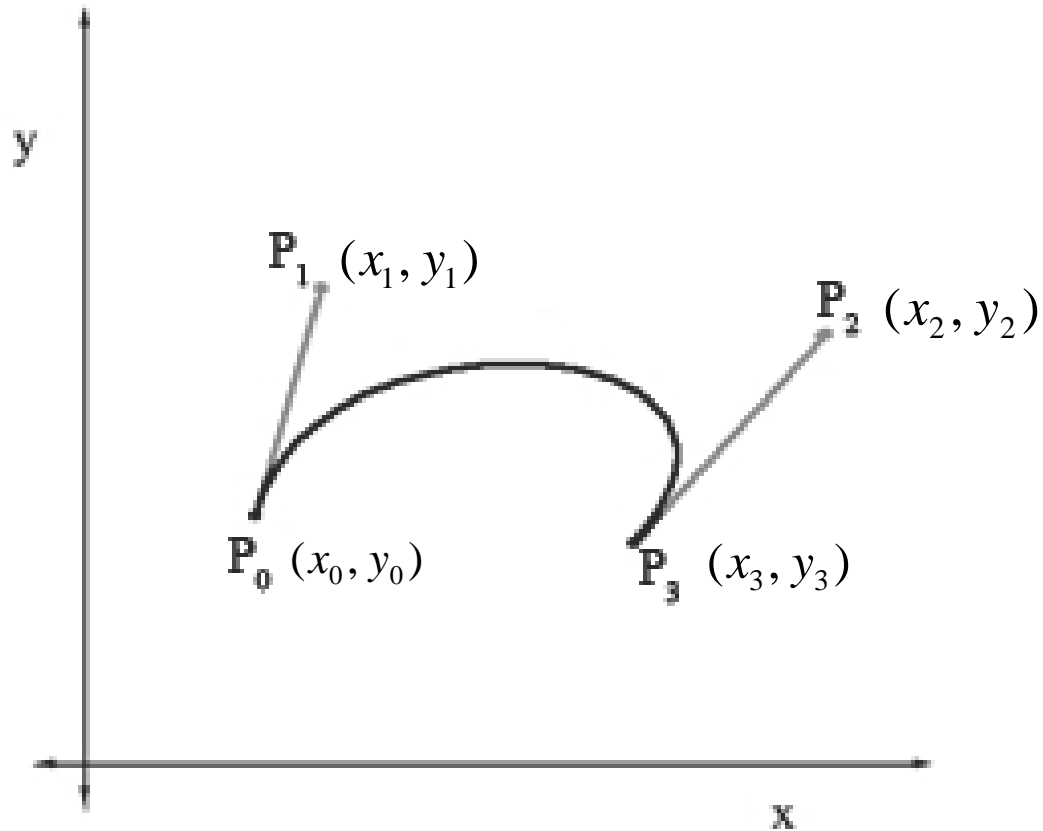
$$x = x_0(1-t)^3 + 3x_1t(1-t)^2 + 3x_2t^2(1-t) + x_3t^3$$

$$y = y_0(1-t)^3 + 3y_1t(1-t)^2 + 3y_2t^2(1-t) + y_3t^3$$

(x_0, y_0) and (x_3, y_3) are curve endpoints

(x_1, y_1) and (x_2, y_2) are guidepoints

A Bezier Curve



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Bezier Curves

Mathematically, we verified that:

Slope of a handle is same as tangent at endpoint

i.e., the tangent at (x_0, y_0) has same slope as the segment joining (x_0, y_0) to (x_1, y_1)

Graphics Curve in General Form

Curve is specified by 2 equations, one is:

$$x = x_0(1-t)^3 + 3x_1t(1-t)^2 + 3x_2t^2(1-t) + x_3t^3$$

Which can be re-written as

$$\begin{aligned} x = & \quad x_0 \quad t^0 \quad (1-t)^3 \\ & + 3 \quad x_1 \quad t^1 \quad (1-t)^2 \\ & + 3 \quad x_2 \quad t^2 \quad (1-t)^1 \\ & + \quad x_3 \quad t^3 \quad (1-t)^0 \end{aligned}$$

General Form of Bezier Curve

This equation

$$\begin{aligned}x = & x_0 t^0 (1-t)^3 \\ & + 3 x_1 t^1 (1-t)^2 \\ & + 3 x_2 t^2 (1-t)^1 \\ & + x_3 t^3 (1-t)^0\end{aligned}$$

can be re-written as

$$\begin{aligned}x = & \frac{3!}{0!(3-0)!} x_0 t^0 (1-t)^3 \\ & + \frac{3!}{1!(3-1)!} x_1 t^1 (1-t)^2 \\ & + \frac{3!}{2!(3-2)!} x_2 t^2 (1-t)^1 \\ & + \frac{3!}{3!(3-3)!} x_3 t^3 (1-t)^0\end{aligned}$$

General Form of Bezier Curve

This form

$$\begin{aligned}x = & \frac{3!}{0!(3-0)!} x_0 t^0 (1-t)^3 \\ & + \frac{3!}{1!(3-1)!} x_1 t^1 (1-t)^2 \\ & + \frac{3!}{2!(3-2)!} x_2 t^2 (1-t)^1 \\ & + \frac{3!}{3!(3-3)!} x_3 t^3 (1-t)^0\end{aligned}$$

can be re-written as

$$x = \sum_{k=0}^n \frac{n!}{k!(n-k)!} x_k t^k (1-t)^{(n-k)}$$



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General Form of Bezier Curve

Hence, the equations are (using $n=3$, for 4 points)

$$x = \sum_{k=0}^n \frac{n!}{k!(n-k)!} x_k t^k (1-t)^{(n-k)}$$

$$y = \sum_{k=0}^n \frac{n!}{k!(n-k)!} y_k t^k (1-t)^{(n-k)}$$

Generic notation,

$$\vec{P} = \sum_{k=0}^n \frac{n!}{k!(n-k)!} \vec{p}_k t^k (1-t)^{(n-k)}$$

Or,
$$\vec{P}(t) = \sum_{k=0}^n \frac{n!}{k!(n-k)!} \vec{p}_k t^k (1-t)^{(n-k)}$$

General Form of Bezier Curve

$$\vec{P}(t) = \sum_{k=0}^n \frac{n!}{k!(n-k)!} \vec{p}_k t^k (1-t)^{(n-k)}$$

Can be re-written as,

$$\vec{P}(t) = \sum_{k=0}^n \vec{p}_k \frac{n!}{k!(n-k)!} t^k (1-t)^{(n-k)}$$

Or,

$$\vec{P}(t) = \sum_{k=0}^n \vec{p}_k BEZ_{k,n}(t)$$

where the organizer can choose n , and the user then supplies $n+1$ points.

General Form of Bezier Curve

$$\vec{P}(t) = \sum_{k=0}^n \vec{p}_k \text{BEZ}_{k,n}(t)$$

is,

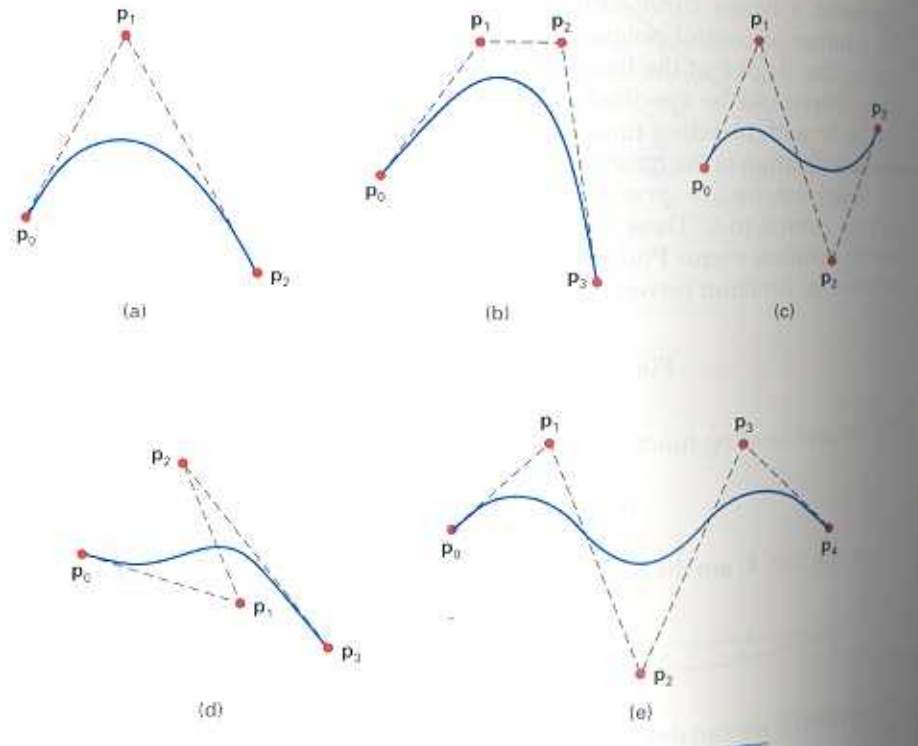
$$\vec{P}(t) = \sum_{k=0}^n \vec{p}_k \frac{n!}{k!(n-k)!} t^k (1-t)^{(n-k)}$$

Most common is $n=3$, some use $n=2$, and $n=4$.

Abandon notion of handles, and use notion of guidepoints.

General Form of Bezier Curve

Most common is $n=3$, some use $n=2$, and $n=4$.



Bezier Curve in Matrix Notation

Consider the familiar case

$$x = x_0(1-t)^3 + 3x_1t(1-t)^2 + 3x_2t^2(1-t) + x_3t^3$$

It expands to

$$\begin{aligned}x &= x_0 - 3x_0t + 3x_0t^2 - x_0t^3 \\ &\quad + 3x_1t - 6x_1t^2 + 3x_1t^3 \\ &\quad + 3x_2t^2 - 3x_2t^3 \\ &\quad + x_3t^3\end{aligned}$$

Towards Matrix Notation

$$\begin{aligned}x &= x_0 - 3x_0t + 3x_0t^2 - x_0t^3 \\ &\quad + 3x_1t - 6x_1t^2 + 3x_1t^3 \\ &\quad \quad + 3x_2t^2 - 3x_2t^3 \\ &\quad \quad \quad + x_3t^3\end{aligned}$$

Gives

$$\begin{aligned}x &= t^3 (-1x_0 + 3x_1 - 3x_2 + x_3) \\ &\quad + t^2 (3x_0 - 6x_1 + 3x_2) \\ &\quad + t (-3x_0 + 3x_1) \\ &\quad + t^0 (x_0)\end{aligned}$$

Towards Matrix Notation

$$\begin{aligned}x &= t^3(-1x_0 + 3x_1 - 3x_2 + x_3) \\ &+ t^2(3x_0 - 6x_1 + 3x_2) \\ &+ t(-3x_0 + 3x_1) \\ &+ t^0(x_0)\end{aligned}$$

Can be written as

$$x = [t^3 \quad t^2 \quad t \quad 1] \begin{bmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 3 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

Matrix notation

Suppose we have $3 \text{ Apples} + 5 \text{ Bananas} = \10

$6 \text{ Apples} + 7 \text{ Bananas} = \15

What is cost of Apple? cost of Banana?

Can write as $3A + 5B = 10$

$6A + 7B = 15$

In matrix notation, get

$$\begin{bmatrix} 3 & 5 \\ 6 & 7 \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} 10 \\ 15 \end{bmatrix}$$

Matrix notation

Using matrix notation,

then would “solve this Matrix system”

$$\begin{bmatrix} 3 & 5 \\ 6 & 7 \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} 10 \\ 15 \end{bmatrix}$$

for $\begin{bmatrix} A \\ B \end{bmatrix}$

by finding inverse matrix of $\begin{bmatrix} 3 & 5 \\ 6 & 7 \end{bmatrix}$

This is studied in class on

Matrix Algebra or Linear Algebra.

Matrix Notation

Matrices are also very useful in Computer Graphics for dealing with rotations and 3-dimensional projections

For now, we only care about the notation; i.e., that we can write in one form (English) or the other (matrix).

$$\begin{array}{rcl} & | & | \\ & | & | \\ 3 \text{ Apples} + 5 \text{ Bananas} & = & \$10 \\ 6 \text{ Apples} + 7 \text{ Bananas} & = & \$15 \end{array} \quad \begin{bmatrix} 3 & 5 \\ 6 & 7 \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} 10 \\ 15 \end{bmatrix}$$

Back To Bezier Curves

We had

$$\begin{aligned}x &= t^3(-1x_0 + 3x_1 - 3x_2 + x_3) \\ &+ t^2(3x_0 - 6x_1 + 3x_2) \\ &+ t(-3x_0 + 3x_1) \\ &+ t^0(x_0)\end{aligned}$$

Wrote as

$$x = \begin{bmatrix} t^3 & t^2 & t & 1 \end{bmatrix} \begin{bmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 3 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

Back To Bezier Curves

This

$$x = [t^3 \quad t^2 \quad t \quad 1] \begin{bmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 3 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

has same form for y

Generic equation:

$$\vec{P}(t) = [t^3 \quad t^2 \quad t \quad 1] \cdot M_{Bez} \cdot \begin{bmatrix} \vec{p}_0 \\ \vec{p}_1 \\ \vec{p}_2 \\ \vec{p}_3 \end{bmatrix}$$



Recall the Polynomial Notation

For curve, $\vec{P}(t) = \sum_{k=0}^n \vec{p}_k \text{BEZ}_{k,n}(t)$

$$\vec{P}(t) = [t^3 \quad t^2 \quad t \quad 1] \cdot M_{\text{Bez}} \cdot \begin{bmatrix} \vec{p}_0 \\ \vec{p}_1 \\ \vec{p}_2 \\ \vec{p}_3 \end{bmatrix}$$

For surface, $\vec{P}(t,s) = \sum_{j=0}^m \sum_{k=0}^n \vec{p}_{j,k} \text{BEZ}_{j,m}(s) \text{BEZ}_{k,n}(t)$



Bezier Surfaces

We have $\vec{P}(t, s) = \sum_{j=0}^m \sum_{k=0}^n \vec{p}_{j,k} \text{BEZ}_{j,m}(s) \text{BEZ}_{k,n}(t)$

Or, for $m=n=3$

$$\vec{P}(t, s) = [t^3 \quad t^2 \quad t \quad 1] \cdot M_{Bez} \cdot \begin{bmatrix} \vec{p}_{00} & \vec{p}_{01} & \vec{p}_{02} & \vec{p}_{03} \\ \vec{p}_{10} & \vec{p}_{11} & \vec{p}_{12} & \vec{p}_{13} \\ \vec{p}_{20} & \vec{p}_{21} & \vec{p}_{22} & \vec{p}_{23} \\ \vec{p}_{30} & \vec{p}_{31} & \vec{p}_{32} & \vec{p}_{33} \end{bmatrix} \cdot M_{Bez}^T \begin{bmatrix} s^3 \\ s^2 \\ s \\ 1 \end{bmatrix}$$

Bezier Surfaces

We need

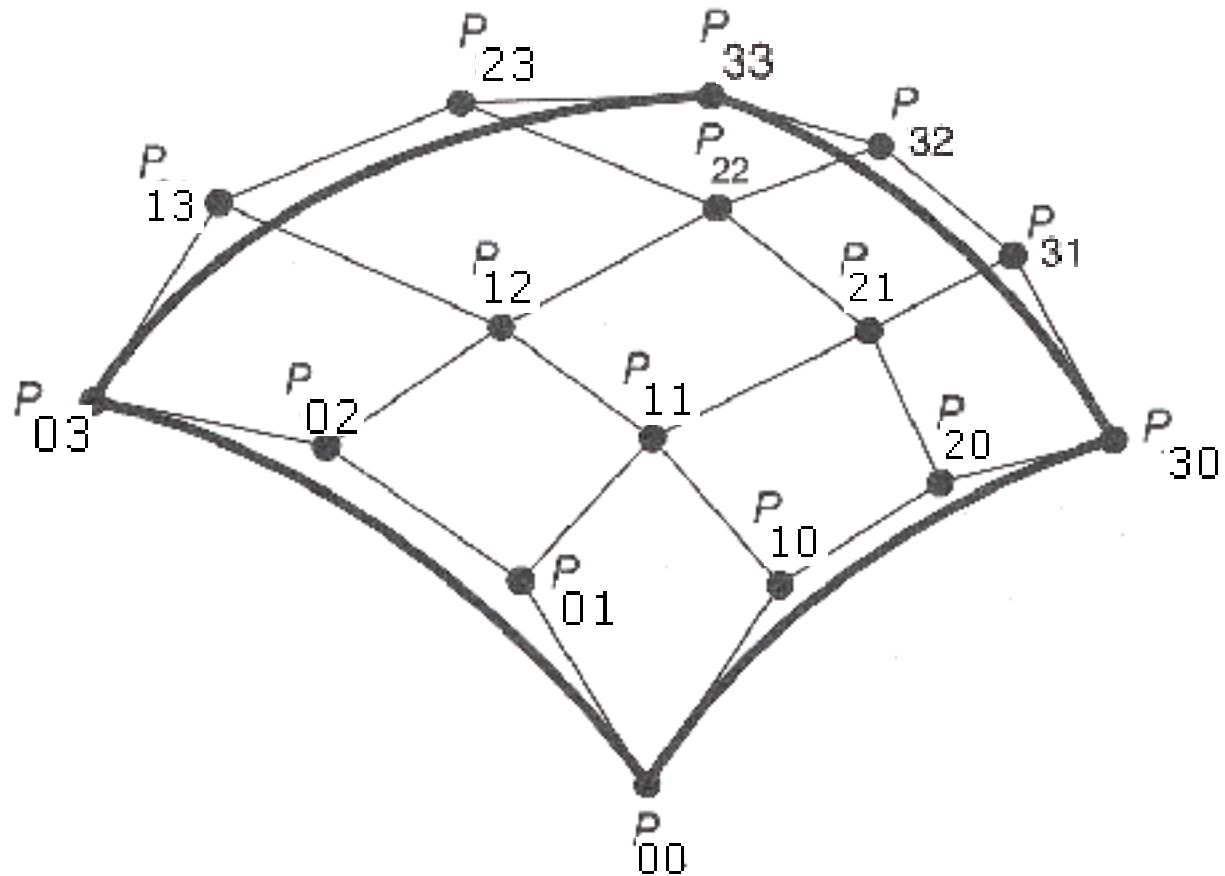


Figure adapted from Princeton Web site

Some Properties of Bezier Surfaces

- 1) Four corners are like Tent anchors, i.e., they are tied down to fixed points. (Interpolation)
- 2) Along any border, the surface behaves as a single Bezier curve.
- 3) Just as with single curve, the surface fits in the Convex Hull of the specified points

Some Properties of Bezier Surfaces

- 4) Because the four borders are explicit Bezier curves, they can be linked to neighboring patches, by making the common border the same Bezier curve, i.e., the same four control points.